

Riemannian Submersion from \mathbb{S}^7 – Sphere ¹

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Abstract

In this paper, we construct an almost quaternion structure which is integrable in the horizontal bundle of the Riemannian submersion $\pi : \mathbb{S}^7 \rightarrow \mathbb{S}^4(\frac{1}{2})$.

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1 Preliminaries

Let M and B be smooth Riemannian manifolds. A Riemannian submersion $\pi : M \rightarrow B$ is a mapping of M onto B satisfying the following axioms;

S1. π has maximal rank; that is, each derivative map π_* of π is onto. Hence, for each $q \in B$, $\pi^{-1}(q)$ is a submanifold of M of dimension $\dim M - \dim B$ where the submanifolds $\pi^{-1}(q)$ are called *fibers* of M . A vector field on M is called *vertical* if it is tangent to a fiber and *horizontal* if orthogonal to in the fiber.

S2. π_* preserves lengths of horizontal vectors; that is, the isomorphism

$$\pi_{*p} : \ker(\pi_{*p})^\perp \rightarrow T_q B$$

is an isometry, where $T_q B$ is tangent space of B at q and $p \in \pi^{-1}(q)$.

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For a Riemannian submersion $\pi : M \rightarrow B$, let \mathcal{V} and \mathcal{H} denote the projections of the tangent spaces of M onto the subspaces of vertical and horizontal vectors, respectively. The letters U, V, W will always denote vertical vector fields, and X, Y, Z horizontal vector fields. Following O'Neill [8] we define the tensor T of type $(1, 2)$ for arbitrary vector fields E and F by

$$T_E F = \mathcal{H}\nabla_{\mathcal{V}E}\mathcal{V}F + \mathcal{V}\nabla_{\mathcal{V}E}\mathcal{H}F$$

where $\mathcal{V}E, \mathcal{H}E$, etc, denote the vertical and horizontal projections of the vector field E . We denote the set of all vector fields on M by $\mathcal{X}(M)$, the set of vertical vector fields by $\mathcal{V}\mathcal{X}(M)$ and the set of horizontal vector fields by $\mathcal{H}\mathcal{X}(M)$. O'Neill has described the following three properties of the tensor T :

- (1) T_E is a skew-symmetric linear operator on the tangent space of M and reverses horizontal and vertical subspaces.
- (2) $T_E = T_{\mathcal{V}E}$, that is, T is vertical.
- (3) For vertical vector fields V and W , T is symmetric, i.e., $T_V W = T_W V$.

In fact, along a fiber, T is the second fundamental form of the fiber provided we restrict ourselves to vertical vector fields.

Now, we simply dualize the definition of T by reversing \mathcal{V} and \mathcal{H} define the integrability tensor A as follows.

For arbitrary vector fields E and F ,

$$A_E F = \mathcal{H}\nabla_{\mathcal{H}E}\mathcal{V}F + \mathcal{V}\nabla_{\mathcal{H}E}\mathcal{H}F$$

- (1') A_E is a skew-symmetric operator on $\mathcal{X}(M)$ reversing the horizontal and vertical subspaces.
- (2') $A_E = A_{\mathcal{H}E}$, that is, A is horizontal.
- (3') For horizontal vector fields X, Y the tensor A is alternating, i.e., $A_X Y = -A_Y X$.

Definition 1 A basic vector field is a horizontal vector field X which is π related to a vector field X_* on B , i.e., $\pi_*(X_p) = X_{*\pi(p)}$ for all $p \in M$.

Lemma 1 If X and Y are basic vector fields on M which are π -related to X_* and Y_* respectively on B . Then

1. $\langle X, Y \rangle = \langle X_*, Y_* \rangle^* \circ \pi$, where \langle, \rangle is the metric on M , and \langle, \rangle^* the metric on B .
2. $\mathcal{H}[X, Y]$ is basic and is π -related to $[X_*, Y_*]$
3. $\mathcal{H}\nabla_X Y$ is basic and is π -related to $\nabla_{X_*}^* Y_*$, where ∇^* is the Riemannian connection on B .

Lemma 2 Let X and Y be horizontal vector fields, V and W be vertical vector fields. Then each of the following holds:

1. $A_X Y = \frac{1}{2}\mathcal{V}[X, Y]$.

2. $\nabla_V W = T_V W + \hat{\nabla}_V W$, where $\hat{\nabla}$ denotes the Riemannian connection along a fiber with respect to the induced metric.

3. a) $\nabla_V X = \mathcal{H}\nabla_V X + T_V X$,

b) If X is basic, $\mathcal{H}\nabla_V X = A_X V$.

4. $\nabla_X V = A_X V + \mathcal{V}\nabla_X V$.

5. $\nabla_X Y = \mathcal{H}\nabla_X Y + A_X Y$.

The proofs of these results are found in O'Neill [8] and R.H. Escobales [1].

Let \mathcal{R} denote the curvature tensor of M , and \mathcal{R}^* the curvature tensor of B . Since there is no danger of ambiguity, we will denote the horizontal lift of \mathcal{R}^* by \mathcal{R}^* as well. Following O'Neill [8] we set $\langle \mathcal{R}_{h_1 h_2}^* h_3, h_4 \rangle = \langle \mathcal{R}_{h_1^* h_2^*}^* h_3^*, h_4^* \rangle^*$ where h_i are horizontal vectors and $\pi_*(h_i) = h_i^*$.

For E and F , linearly independent vectors, we denote the tangent plane spanned by these two vectors by $P_E F$. In general, if X is a horizontal vector, then $\pi_* X$ is denoted by X_* . K, K_* and \hat{K} will denote the sectional curvature of M, B and the fiber $\pi^{-1}(q)$, respectively.

Theorem 1 Let $\pi : M \rightarrow B$ be a Riemannian submersion.

(a) Then for horizontal vector fields X, Y, Z and H

$$\langle \mathcal{R}_{XY}^* Z, H \rangle =$$

$$\langle \mathcal{R}_{XY} Z, H \rangle + 2 \langle A_X Y, A_Z H \rangle - \langle A_Y Z, A_X H \rangle - \langle A_Z X, A_Y H \rangle,$$

(b) If X and Y are horizontal, and V and W are vertical vector fields, then

$$\begin{aligned} \langle \mathcal{R}_{XV} Y, W \rangle = & \langle (\nabla_X T)_V W, Y \rangle + \langle (\nabla_V A)_X Y, W \rangle - \langle T_V X, T_W Y \rangle \\ & + \langle A_X V, A_Y W \rangle. \end{aligned}$$

Corollary 1 Let $\pi : M \rightarrow B$ be a Riemannian submersion. Then for linearly independent horizontal vector fields X and Y and linearly independent vertical vector fields V and W we obtain the following relations:

$$(a) \quad K(P_V W) = \hat{K}(P_V W) - \frac{\langle T_V V, T_W W \rangle - \langle T_V W, T_V W \rangle}{\langle V, V \rangle \langle W, W \rangle - \langle V, W \rangle^2},$$

$$(b) \quad K(P_X V) = \frac{\langle (\nabla_X T)_V V, X \rangle + \langle A_X V, A_X V \rangle - \langle T_V X, T_V X \rangle}{\langle X, X \rangle \langle V, V \rangle},$$

$$(c) \quad K_*(P_{X_*} Y_*) = K(P_X Y) + \frac{3 \langle A_X Y, A_X Y \rangle}{\langle X, X \rangle \langle Y, Y \rangle - \langle X, Y \rangle^2}.$$

Corollary 2 Let $\pi : M \rightarrow B$ be a Riemannian submersion with totally geodesic fibers. Then for orthonormal horizontal vector fields X and Y and a vertical vector field V of unit length

- (a) $K(P_X V) = \langle A_X V, A_X V \rangle$,
- (b) $K_*(P_{X_*} Y_*) = K(P_X Y) + 3 \langle A_X Y, A_X Y \rangle$.

Proof. Immediate from Corollary 1.

Corollary 3 Let $\pi : M \rightarrow B$ be a Riemannian submersion with totally geodesic fibers. If X and Y are horizontal, and V and W are vertical, then;

$$\langle (\nabla_V A)_X Y, W \rangle + \langle (\nabla_W A)_X Y, V \rangle = 0.$$

Proof. See R.H. Escobales [2].

Definition 2 Let M be an n -dimensional manifold with a 3-dimensional vector bundle N consisting of tensors of type $(1,1)$ over M such that in any coordinate neighborhood \mathcal{U} of M , there is a local basis $\{F, G, H\}$ of N with

$$F^2 = -I, \quad G^2 = -I, \quad H^2 = -I,$$

(1)

$$GH = -HG = F, \quad HF = -FH = G, \quad FG = -GF = H,$$

where, I denotes the identity tensor of type $(1,1)$ in M .

Such a local basis $\{F, G, H\}$ is called a *canonical local basis* of the bundle N in \mathcal{U} . The bundle N is called an *almost quaternion structure* in M , and M with N an *almost quaternion manifold*, which will be denoted by (M, N) . An almost quaternion manifold M is of dimension $n = 4m$ ($m \geq 1$).

Definition 3 Let (M, N) be an almost quaternion manifold with a canonical local basis of N in a coordinate neighborhood \mathcal{U} . We now assume that there exists a system of coordinates (x^l) in each \mathcal{U} with respect to which F, G and H have components of the form

$$(2) \quad F = \begin{pmatrix} 0 & -E & 0 & 0 \\ E & 0 & 0 & 0 \\ 0 & 0 & 0 & -E \\ 0 & 0 & E & 0 \end{pmatrix}, \quad G = \begin{pmatrix} 0 & 0 & -E & 0 \\ 0 & 0 & 0 & E \\ E & 0 & 0 & 0 \\ 0 & -E & 0 & 0 \end{pmatrix},$$

$$H = \begin{pmatrix} 0 & 0 & 0 & -E \\ 0 & 0 & -E & 0 \\ 0 & E & 0 & 0 \\ E & 0 & 0 & 0 \end{pmatrix}$$

where E denotes the identity $(m \times m)$ -matrix. In such a case, the given almost quaternion structure N is said to be integrable.

2 Main Results

Let us consider the following Riemannian submersion

$$\pi : \mathbb{S}^7 \rightarrow \mathbb{S}^4\left(\frac{1}{2}\right)$$

where \mathbb{S}^7 is 7-dimensional unit sphere and $\mathbb{S}^4\left(\frac{1}{2}\right)$ is 4-dimensional sphere with radius $\frac{1}{2}$. The existence of π is guaranteed by [1, Theorem 3.5]. Also, in [1] Escobales shows that this Riemannian submersion π has connected totally geodesic fibers and also the fibers are equal to the 3-dimensional unit sphere \mathbb{S}^3 . The fibers \mathbb{S}^3 are both totally geodesic and totally umbilical submanifolds of \mathbb{S}^7 .

Let $\{U, V, W\}$ be an orthonormal basis field on the fiber \mathbb{S}^3 , i.e. $\{U, V, W\} \in \mathcal{VX}(\mathbb{S}^7)$. Since \mathbb{S}^3 is both totally geodesic and totally umbilical submanifold of \mathbb{S}^7 we can assume that orthonormal vertical vector fields U, V and W are geodesic vector fields. We fix these vector fields and define three mappings i, j and k on $\mathcal{HX}(\mathbb{S}^7)$ as follows

$$i, j, k : \mathcal{HX}(\mathbb{S}^7) \rightarrow \mathcal{HX}(\mathbb{S}^7)$$

are defined by $i(X) = A_X U$, $j(X) = A_X V$, and $k(X) = A_X W$ for any horizontal vector field X . We see that these mappings are all tensor fields of type $(1, 1)$.

Lemma 3 *The tensors i, j and k which are defined above are skew-symmetric with respect to metric on \mathbb{S}^7 .*

Proof. We will only prove one since the proofs of others are similar. For any horizontal vector fields X and Y ,

$$(3) \quad 0 = Y \langle X, U \rangle = \langle \nabla_Y X, U \rangle + \langle X, \nabla_Y U \rangle = \langle A_Y X, U \rangle + \langle X, A_Y U \rangle ,$$

where we use Lemma 2-(5). Interchanging X and Y we have

$$(4) \quad 0 = \langle A_X Y, U \rangle + \langle Y, A_X U \rangle .$$

Since $A_X Y = -A_Y X$, (3) and (4) yields

$\langle A_Y U, X \rangle + \langle A_X U, Y \rangle = 0$, that is, $\langle i(X), Y \rangle = -\langle i(Y), X \rangle$. Hence the proof completes.

Lemma 4 *The tensors i, j and k are all isometries with respect to the metric on \mathbb{S}^7 .*

Proof. Again, we will only prove one since the proofs of others are similar. From the Corollary 1-(b) we have

$$K(P_X V) = \frac{\langle (\nabla_X T)_V V, X \rangle + \langle A_X V, A_X V \rangle - \langle T_V X, T_V X \rangle}{\langle X, X \rangle \langle V, V \rangle}$$

Since the fiber \mathbb{S}^3 is totally geodesic, T is identically zero. On the other hand, we know that $K(P_X V) = 1$, so we have

$$1 = \frac{\langle A_X V, A_X V \rangle}{\langle X, X \rangle}$$

Hence we obtain $\langle A_X V, A_X V \rangle = \langle X, X \rangle$, that is, $\|j(X)\|^2 = \|X\|^2 \Rightarrow \|j(X)\| = \|X\|$. Which means that j is an isometry.

Lemma 5 *Let X be any horizontal vector field on $\mathcal{HX}(\mathbb{S}^7)$. Then the set $\{X, i(X), j(X), k(X)\}$ is an orthogonal basis on $\mathcal{HX}(\mathbb{S}^7)$.*

Proof. $\langle X, i(X) \rangle = \langle X, A_X U \rangle = -\langle U, A_X X \rangle = 0$, since $A_X X = 0$. Similarly,

$$(5) \quad \langle X, j(X) \rangle = \langle X, k(X) \rangle = 0 .$$

$\langle j(X), k(X) \rangle = \langle A_X V, A_X W \rangle$. From the Theorem 1-(b) we have $\langle \mathcal{R}_{XV} Y, W \rangle = \langle (\nabla_V A)_X Y, W \rangle + \langle A_X V, A_Y W \rangle$, since $T \equiv 0$.

Put $Y = X$ in this equation,

$\mathcal{R}_{XV} X = 1 \cdot \{\langle X, X \rangle V - \langle X, V \rangle X\} = \|X\|^2 V$, since

$\langle X, V \rangle = 0$, thus

$\langle \mathcal{R}_{XV} X, W \rangle = \|X\|^2 \langle V, W \rangle = 0$, since $\langle V, W \rangle = 0$.

On the other hand, we have from Corollary 3, $\langle (\nabla_V A)_X X, W \rangle = 0$. Thus we get $\langle A_X V, A_X W \rangle = 0$. Similarly,

$$(6) \quad \langle i(X), j(X) \rangle = \langle i(X), k(X) \rangle = 0 .$$

From the (5) and (6) the result follows.

Lemma 6 $i^2 = -I, \quad j^2 = -I, \quad k^2 = -I$, where I denotes the identity tensor of type $(1, 1)$ in \mathbb{S}^7 .

Proof. We will only prove one since the proofs of others are similar. We must show that $i^2(X) = -X$, for any horizontal vector field X .

Let Y be an arbitrary horizontal vector field, since i is skew-symmetric we write

$\langle i^2(X), Y \rangle = \langle i(i(X)), Y \rangle = -\langle i(X), i(Y) \rangle$. On the other hand we

know that i is an isometry, thus we have

$-\langle i(X), i(Y) \rangle = -\langle X, Y \rangle$. Finally, $\langle i^2(X), Y \rangle = -\langle X, Y \rangle$. From

this, we deduce that $i^2(X) = -X$.

Lemma 7 $ij = -ji, \quad ik = -ki, \quad jk = -kj.$

Proof. We will only prove one since the proofs of others are similar. For example, $ij = -ji$. We must show that $ij(X) = -ji(X)$ for any horizontal vector field X .

Let Y be an arbitrary horizontal vector field, since i is skew-symmetric we can write

$\langle ij(X), Y \rangle = \langle i(A_X V), Y \rangle = -\langle A_X V, i(Y) \rangle = -\langle A_X V, A_Y U \rangle$. Here we use Theorem 1-(b) and $T \equiv 0$ we get,

$\langle \mathcal{R}_{XV} Y, U \rangle = \langle (\nabla_V A)_X Y, U \rangle + \langle A_X V, A_Y U \rangle$. But

$\mathcal{R}_{XV} Y = 1 \cdot \{ \langle X, Y \rangle V - \langle V, Y \rangle X \} = \langle X, Y \rangle V$,

hence $\langle \mathcal{R}_{XV} Y, U \rangle = \langle X, Y \rangle \langle V, U \rangle = 0$, since $\langle V, U \rangle = 0$.

Thus we have, $-\langle A_X V, A_Y U \rangle = \langle (\nabla_V A)_X Y, U \rangle$.

On the other hand we have from Corollary 3

$\langle (\nabla_V A)_X Y, U \rangle = -\langle (\nabla_U A)_X Y, V \rangle$. Therefore we obtain

$\langle ij(X), Y \rangle = -\langle (\nabla_U A)_X Y, V \rangle$, this is equal to $\langle A_X U, A_Y V \rangle$, using properties of A (1') and (3'), we get

$\langle A_X U, A_Y V \rangle = -\langle A_Y A_X U, V \rangle = \langle A_{A_X U} Y, V \rangle$
 $= -\langle A_{A_X U} V, Y \rangle = -\langle ji(X), Y \rangle$.

From this, we deduce that $ij(X) = -ji(X)$.

Lemma 8 $ij = k \quad \text{or} \quad ij = -k.$

Proof. We must show that $ij(X) = k(X)$ or $ij(X) = -k(X)$ for any $X \in \mathcal{HX}(\mathbb{S}^7)$. If $X = 0$, then it is clear. Therefore we can assume $X \neq 0$. Since $ij(X) \in \mathcal{HX}(\mathbb{S}^7)$ and $\{X, i(X), j(X), k(X)\}$ is an orthogonal basis on $\mathcal{HX}(\mathbb{S}^7)$, we can write

$ij(X) = \lambda_1 X + \lambda_2 i(X) + \lambda_3 j(X) + \lambda_4 k(X)$, where $\lambda_a (1 \leq a \leq 4)$ are real-valued functions on fiber \mathbb{S}^3 , where,

$$\lambda_1 = \frac{\langle ij(X), X \rangle}{\langle X, X \rangle}, \quad \lambda_2 = \frac{\langle ij(X), i(X) \rangle}{\langle i(X), i(X) \rangle}, \quad \lambda_3 = \frac{\langle ij(X), j(X) \rangle}{\langle j(X), j(X) \rangle}, \quad \lambda_4 = \frac{\langle ij(X), k(X) \rangle}{\langle k(X), k(X) \rangle}$$

$$\langle ij(X), X \rangle = \langle A_{A_X V} U, X \rangle = -\langle A_X U, A_X V \rangle \\ = -\langle i(X), j(X) \rangle = 0, \text{ so}$$

$$(7) \quad \langle ij(X), X \rangle = 0.$$

$\langle ij(X), i(X) \rangle = \langle A_{A_X V} U, A_X U \rangle = A_{A_X V} \langle U, A_X U \rangle - \langle U, A_{A_X V} A_X U \rangle$
 $= \langle U, A_{A_X V} A_X U \rangle$, since $\langle U, A_X U \rangle = 0$. From the Theorem 1-(b) we can write

$\langle U, A_{A_X V} A_X U \rangle = \langle \mathcal{R}_{(A_X V)U} X, U \rangle - \langle (\nabla_U A)_{A_X V} X, U \rangle$. Where, since

$\mathcal{R}_{(A_X V)U} X = 1 \cdot \{ \langle X, A_X V \rangle U - \langle X, U \rangle A_X V \} = 0$, we obtain

$\langle ij(X), i(X) \rangle = -\langle (\nabla_U A)_{A_X V} X, U \rangle$. But from the Corollary 3 we deduce that

$$-\langle (\nabla_U A)_{A_X V} X, U \rangle = 0, \text{ so}$$

$$(8) \quad \langle ij(X), i(X) \rangle = 0.$$

Similarly,

$$(9) \quad \langle ij(X), j(X) \rangle = 0 .$$

Now, we compute $\langle ij(X), k(X) \rangle$.

$\langle ij(X), k(X) \rangle = \langle A_{A_X V} U, A_X W \rangle = - \langle A_{A_X V} A_X W, U \rangle$, since $A_{A_X V} A_X W$ is vertical, we can write $A_{A_X V} A_X W = \alpha U + \beta V + \gamma W$, where α, β and γ are real-valued functions on \mathbb{S}^3 .

$$\begin{aligned} \langle A_{A_X V} A_X W, V \rangle &= - \langle A_{A_X V} V, A_X W \rangle = - \langle j^2(X), k(X) \rangle \\ &= \langle X, k(X) \rangle = 0. \end{aligned}$$

Similarly,

$$\langle A_{A_X V} A_X W, W \rangle = \langle X, j(X) \rangle = 0. \text{ Thus we have}$$

$A_{A_X V} A_X W = \alpha U$. Let put $A_X V = Y$ and $A_X W = Z$. Then from the Corollary 2-(c) we get

$$\begin{aligned} \frac{3\langle A_Y Z, A_Y Z \rangle}{\langle Y, Y \rangle \langle Z, Z \rangle - \langle Y, Z \rangle^2} &= K_*(P_Y Z_*) - K(P_Y Z) = 4 - 1 = 3 \\ \Rightarrow \langle A_Y Z, A_Y Z \rangle &= \|Y\|^2 \|Z\|^2, \end{aligned}$$

$$\text{since } \langle Y, Z \rangle = \langle A_X V, A_X W \rangle = \langle j(X), k(X) \rangle = 0.$$

On the other hand $\|Y\|^2 = \langle A_X V, A_X V \rangle = \langle X, X \rangle = \|X\|^2$ and

$$\|Z\|^2 = \langle A_X W, A_X W \rangle = \langle X, X \rangle = \|X\|^2, \text{ so}$$

$$\langle A_Y Z, A_Y Z \rangle = \|X\|^4.$$

$\|X\|^4 = \langle A_Y Z, A_Y Z \rangle = \langle \alpha U, \alpha U \rangle = \alpha^2 \langle U, U \rangle = \alpha^2 \cdot 1 = \alpha^2$, so $\alpha = \pm \|X\|^2$. Hence,

$$\begin{aligned} \langle ij(X), k(X) \rangle &= - \langle A_{A_X V} A_X W, U \rangle \\ &= - \langle \pm \|X\|^2 U, U \rangle = \mp \|X\|^2. \text{ Finally} \end{aligned}$$

$$(10) \quad \lambda_4 = \frac{\langle ij(X), k(X) \rangle}{\langle k(X), k(X) \rangle} = \frac{\mp \|X\|^2}{\|X\|^2} = \mp 1 .$$

From the (7), (8) and (9), we get $\lambda_1 = \lambda_2 = \lambda_3 = 0$ and from the (10), $\lambda_4 = \mp 1$. Thus we have the required result.

Remark 1 In case $ij = k$, we get $ijk = kk = k^2 = -I \Rightarrow ijk = -I$.

If $ij = -k$, then $jik = -ijk = -(-k)k = k^2 = -I \Rightarrow jik = -I$.

In each case, we order i, j and k . such that their triple multiplication is equal to $-I$. Therefore, there will be no matter if we admit $ijk = -I$, so we have $ij = -ji = k$, $ki = -ki = j$, $jk = -kj = i$.

Let us denote by N the subspace of $\mathcal{HX}(\mathbb{S}^7)$ spanned by $\{i(X), j(X), k(X)\}$. By using Lemma 6, Lemma 7, Lemma 8 and Remark 1 we have the following.

Theorem 2 N is an almost quaternion structure in $\mathcal{HX}(\mathbb{S}^7)$.

Corollary 4 Given almost quaternion structure in Theorem above N is integrable.

Proof. We must verify (2) in the Definition 3. For any $X \in \mathcal{HX}(\mathbb{S}^7)$, using Lemma 5 and Remark 1, we can write

$$\begin{aligned} i(X) &= 0.X + 1.i(X) + 0.j(X) + 0.k(X) \\ i(i(X)) &= -1.X + 0.i(X) + 0.j(X) + 0.k(X) \\ i(j(X)) &= 0.X + 0.i(X) + 0.j(X) + 1.k(X) \\ i(k(X)) &= 0.X + 0.i(X) - 1.j(X) + 0.k(X) \end{aligned}$$

Thus the matrix of i ,

$$[i]_{4 \times 4} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}^T = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

Similarly, the matrix of j ,

$$[j]_{4 \times 4} = \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}$$

and the matrix of k ,

$$[k]_{4 \times 4} = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

which means that N is integrable.

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